



**Mingcong Deng** received his B. S. and M. S. degrees in Control Engineering from Northeastern University, China, in 1986 and 1991, and his Ph.D. in Systems Science from Kumamoto University, Japan, in 1997. From 1997 to 2000 he was with Kumamoto University as an assistant professor. From 2000 to 2001 he was with University of Exeter(UK) as research fellow, and then spent one year at the NTT Communication Science Laboratories for human arm dynamics research. Since the end of 2002, he has worked at the Department of Systems Engineering, Okayama University, where he is an associate professor. Prof. Deng is also distinguished professor of Northeastern University and Zhongyuan University of Technology.

Prof. Deng is a member of SICE, ISCIE, IEICE, JSME, ICROS and the IEEE(SM). He serves as a chief editor of International Journal of Advanced Mechatronic Systems and associate editors of some international journals. He has been a chair for many IEEE International Conferences and the other international conferences. His research interests include living body measurement, operator-based nonlinear system modeling, control and fault detection, strong stability-based control, and robust parallel compensation. He has published over 70 research papers and 100 international conference papers.

[deng@qumi.sys.okayama-u.ac.jp](mailto:deng@qumi.sys.okayama-u.ac.jp)

Prof. Mingcong Deng  
Okayama University  
Graduate School of Natural Science and Technology  
3-1-1 Tsushima-Naka  
Okayama 700-8530  
JAPAN